

# LAMPIRAN

## **LAMPIRAN A**

### **Listing Program Arduino**

Berikut ini adalah listing program yang telah dibuat untuk Arduino Uno

```
#include <TimerOne.h>

#include "EmonLib.h"

EnergyMonitor emon1;

EnergyMonitor emon2;

EnergyMonitor emon3;

#include <LiquidCrystal.h>

const int rs = 8, en = 9, d4 = 10, d5 = 11, d6 = 12, d7 = 13;

LiquidCrystal lcd(rs, en, d4, d5, d6, d7);

volatile int i=0,j=0,k=0;

volatile boolean zero_cross=0;

volatile boolean zero_cross2=0;

volatile boolean zero_cross3=0;

unsigned int set_daya=15;

int AC_pin = 0;

int dim2 = 0;

int dim = 0;

int dim3 = 0;

int pas = 8;

int freqStep = 75;

#define beban1 3
```

```
#define beban2 4
#define beban3 5
#define sw1 6
#define sw2 7

void setup()
{
    lcd.begin(16, 2);
    lcd.print("FANSHURI");
    delay(5000);

    pinMode(sw1, INPUT_PULLUP);
    pinMode(sw2, INPUT_PULLUP);

    pinMode(beban1, OUTPUT);
    pinMode(beban2, OUTPUT);
    pinMode(beban3, OUTPUT);

    setting();

    digitalWrite(beban1, HIGH);
    digitalWrite(beban2, HIGH);
    digitalWrite(beban3, HIGH);

    attachInterrupt(0, zero_cross_detect, RISING);
    Timer1.initialize(freqStep);
    Timer1.attachInterrupt(dim_check, freqStep);
    emon1.voltage(0, 320, 1.7);
```

```
emon1.current(3, 11.1);

emon2.voltage(1, 320, 1.7);

emon2.current(4, 11.1);

emon3.voltage(2, 320, 1.7);

emon3.current(5, 11.1);

}

void zero_cross_detect() {

zero_cross = true;

zero_cross2 = true;

zero_cross3 = true;

i=0;

j=0;

k=0;

digitalWrite(beban1, LOW);

digitalWrite(beban2, LOW);

digitalWrite(beban3, LOW);

}

void dim_check() {

if(zero_cross == true) {

if(i>=dim) {

digitalWrite(beban1, HIGH);

i=0;
```

```
zero_cross=false;

}

else {

    i++;
}

if(zero_cross2 == true) {

    if(j>=dim2) {

        digitalWrite(beban2, HIGH);

        j=0;

        zero_cross2=false;

    }

    else {

        j++;

    }

}

if(zero_cross3 == true) {

    if(k>=dim3) {

        digitalWrite(beban3, HIGH);

        k=0;

        zero_cross3=false;

    }

    else {

        k++;

    }

}
```

```
    }

}

void loop()
{
    emon1.calcVI(20,2000);
    wavelengths (crossings), time-out
    emon2.calcVI(20,2000);
    wavelengths (crossings), time-out
    emon3.calcVI(20,2000);
    wavelengths (crossings), time-out

    float realPower1      = emon1.realPower;
    float apparentPower1  = emon1.apparentPower;
    float powerFActor1   = emon1.powerFactor;
    float supplyVoltage1 = emon1.Vrms;
    float Irms1           = emon1.Irms;

    float realPower2      = emon2.realPower;
    float apparentPower2  = emon2.apparentPower;
    float powerFActor2   = emon2.powerFactor;
    float supplyVoltage2 = emon2.Vrms;
    float Irms2           = emon2.Irms;

    float realPower3      = emon3.realPower;
    float apparentPower3  = emon3.apparentPower;
```

```

float powerFActor3      = emon3.powerFactor;

float supplyVoltage3   = emon3.Vrms;

float Irms3            = emon3.Irms;

lcd.setCursor(0,0);lcd.print(" ");

if (supplyVoltage1<10){lcd.print(" ");}
else if (supplyVoltage1>9&&supplyVoltage1<100){lcd.print(" ");}
else if (supplyVoltage1>99&&supplyVoltage1<1000){lcd.print(" ");}

lcd.print(supplyVoltage1,0);lcd.print(" ");

if (supplyVoltage2<10){lcd.print(" ");}
else if (supplyVoltage2>9&&supplyVoltage2<100){lcd.print(" ");}
else if (supplyVoltage2>99&&supplyVoltage2<1000){lcd.print(" ");}

lcd.print(supplyVoltage2,0);lcd.print(" ");

if (supplyVoltage3<10){lcd.print(" ");}
else if (supplyVoltage3>9&&supplyVoltage3<100){lcd.print(" ");}
else if (supplyVoltage3>99&&supplyVoltage3<1000){lcd.print(" ");}

lcd.print(supplyVoltage3,0);lcd.print(" ");

lcd.setCursor(0,1);lcd.print(" ");

lcd.print(Irms1,2);lcd.print(" ");

lcd.print(Irms2,2);lcd.print(" ");

lcd.print(Irms3,2);lcd.print(" ");

if (apparentPower1>set_daya){dim++;if(dim>125){dim=125;}}
else if (apparentPower1<set_daya){dim--;if(dim<0){dim=0;}}
if (apparentPower2>set_daya){dim2++;if(dim2>125){dim2=125;}}
else if (apparentPower2<set_daya){dim2--;if(dim2<0){dim2=0;}}

```

```
if (apparentPower3>set_daya) {dim3++;if(dim3>125) {dim3=125;} }

else if (apparentPower3<set_daya) {dim3--;if(dim3<0) {dim3=0;} }

}

char buff[16];

void setting(){

while(digitalRead(sw2)==1){

lcd.clear();

if(digitalRead(sw1)==0){set_daya++;if
(set_daya>200){set_daya=1;}}

lcd.setCursor(0,0);

lcd.print("PENGATURAN");

lcd.setCursor(0,1);

lcd.print("Daya= ");

lcd.print(set_daya);

delay(200);

}

lcd.clear();

lcd.setCursor(0,0);

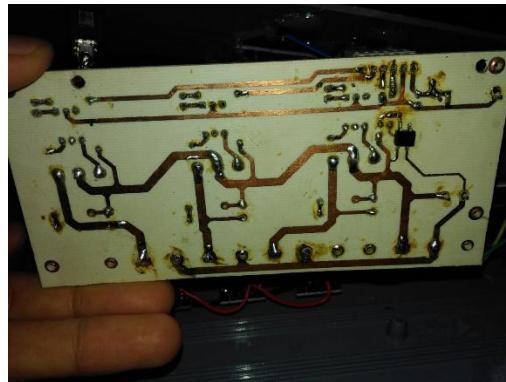
lcd.print("TERSIMPAN.....");

delay(3000);

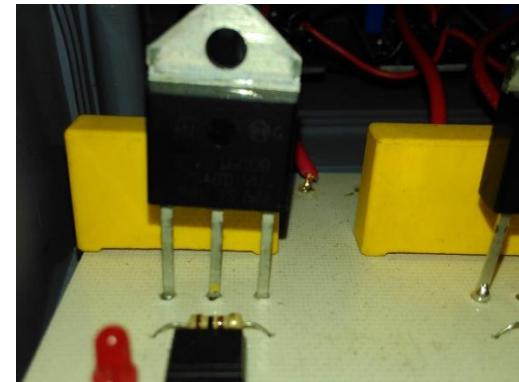
}
```

## LAMPIRAN B

### Dokumentasi Alat



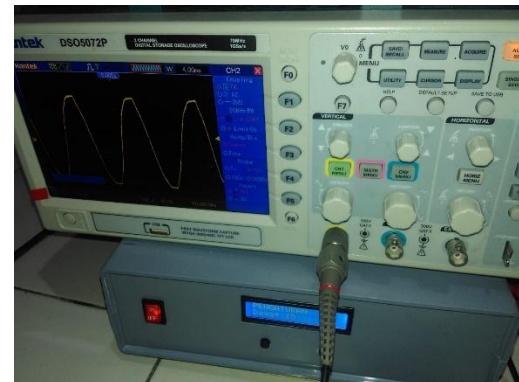
**Gambar A.1** Rangkaian PCB *solid state relay* dan *zero crossing detector*



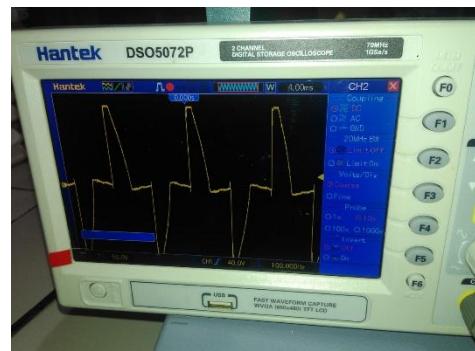
**Gambar A.2** Rangkaian Triac dan MOC3021 untuk *solid state relay*



**Gambar A.3** Pengujian sensor tegangan dengan Variac Slide Regulator AC



**Gambar A.4** Bentuk gelombang AC beban sebelum penyesuaian daya



**Gambar A.5** Bentuk gelombang AC beban setelah penyesuaian daya



**Gambar A.6** Pengukuran daya lampu dengan menggunakan alat ukur standar

## **LAMPIRAN B**

### **Listing Program Arduino**

Berikut ini adalah listing program yang telah dibuat untuk Arduino Uno

```
#include <TimerOne.h>

#include "EmonLib.h"

EnergyMonitor emon1;

EnergyMonitor emon2;

EnergyMonitor emon3;

#include <LiquidCrystal.h>

const int rs = 8, en = 9, d4 = 10, d5 = 11, d6 = 12, d7 = 13;

LiquidCrystal lcd(rs, en, d4, d5, d6, d7);

volatile int i=0,j=0,k=0;

volatile boolean zero_cross=0;

volatile boolean zero_cross2=0;

volatile boolean zero_cross3=0;

unsigned int set_daya=15;

int AC_pin = 0;

int dim2 = 0;

int dim = 0;

int dim3 = 0;

int pas = 8;

int freqStep = 75;

#define beban1 3
```

```
#define beban2 4
#define beban3 5
#define sw1 6
#define sw2 7

void setup()
{
    lcd.begin(16, 2);
    lcd.print("FANSHURI");
    delay(5000);

    pinMode(sw1, INPUT_PULLUP);
    pinMode(sw2, INPUT_PULLUP);

    pinMode(beban1, OUTPUT);
    pinMode(beban2, OUTPUT);
    pinMode(beban3, OUTPUT);

    setting();

    digitalWrite(beban1, HIGH);
    digitalWrite(beban2, HIGH);
    digitalWrite(beban3, HIGH);

    attachInterrupt(0, zero_cross_detect, RISING);
    Timer1.initialize(freqStep);
    Timer1.attachInterrupt(dim_check, freqStep);
    emon1.voltage(0, 320, 1.7);
```

```
emon1.current(3, 11.1);

emon2.voltage(1, 320, 1.7);

emon2.current(4, 11.1);

emon3.voltage(2, 320, 1.7);

emon3.current(5, 11.1);

}

void zero_cross_detect() {

zero_cross = true;

zero_cross2 = true;

zero_cross3 = true;

i=0;

j=0;

k=0;

digitalWrite(beban1, LOW);

digitalWrite(beban2, LOW);

digitalWrite(beban3, LOW);

}

void dim_check() {

if(zero_cross == true) {

if(i>=dim) {

digitalWrite(beban1, HIGH);

i=0;
```

```
zero_cross=false;

}

else {

    i++;
}

if(zero_cross2 == true) {

    if(j>=dim2) {

        digitalWrite(beban2, HIGH);

        j=0;

        zero_cross2=false;

    }

    else {

        j++;

    }

}

if(zero_cross3 == true) {

    if(k>=dim3) {

        digitalWrite(beban3, HIGH);

        k=0;

        zero_cross3=false;

    }

    else {

        k++;

    }

}
```

```
    }

}

void loop()
{
    emon1.calcVI(20,2000);
    wavelengths (crossings), time-out
    emon2.calcVI(20,2000);
    wavelengths (crossings), time-out
    emon3.calcVI(20,2000);
    wavelengths (crossings), time-out

    float realPower1      = emon1.realPower;
    float apparentPower1  = emon1.apparentPower;
    float powerFActor1   = emon1.powerFactor;
    float supplyVoltage1 = emon1.Vrms;
    float Irms1           = emon1.Irms;

    float realPower2      = emon2.realPower;
    float apparentPower2  = emon2.apparentPower;
    float powerFActor2   = emon2.powerFactor;
    float supplyVoltage2 = emon2.Vrms;
    float Irms2           = emon2.Irms;

    float realPower3      = emon3.realPower;
    float apparentPower3  = emon3.apparentPower;
```

```

float powerFActor3      = emon3.powerFactor;

float supplyVoltage3   = emon3.Vrms;

float Irms3            = emon3.Irms;

lcd.setCursor(0,0);lcd.print(" ");

if (supplyVoltage1<10){lcd.print(" ");}
else if (supplyVoltage1>9&&supplyVoltage1<100){lcd.print(" ");}
else if (supplyVoltage1>99&&supplyVoltage1<1000){lcd.print(" ");}

lcd.print(supplyVoltage1,0);lcd.print(" ");

if (supplyVoltage2<10){lcd.print(" ");}
else if (supplyVoltage2>9&&supplyVoltage2<100){lcd.print(" ");}
else if (supplyVoltage2>99&&supplyVoltage2<1000){lcd.print(" ");}

lcd.print(supplyVoltage2,0);lcd.print(" ");

if (supplyVoltage3<10){lcd.print(" ");}
else if (supplyVoltage3>9&&supplyVoltage3<100){lcd.print(" ");}
else if (supplyVoltage3>99&&supplyVoltage3<1000){lcd.print(" ");}

lcd.print(supplyVoltage3,0);lcd.print(" ");

lcd.setCursor(0,1);lcd.print(" ");

lcd.print(Irms1,2);lcd.print(" ");

lcd.print(Irms2,2);lcd.print(" ");

lcd.print(Irms3,2);lcd.print(" ");

if (apparentPower1>set_daya){dim++;if(dim>125){dim=125;}}
else if (apparentPower1<set_daya){dim--;if(dim<0){dim=0;}}
if (apparentPower2>set_daya){dim2++;if(dim2>125){dim2=125;}}
else if (apparentPower2<set_daya){dim2--;if(dim2<0){dim2=0;}}

```

```
if (apparentPower3>set_daya) {dim3++;if(dim3>125) {dim3=125;} }

else if (apparentPower3<set_daya) {dim3--;if(dim3<0) {dim3=0;} }

}

char buff[16];

void setting(){

while(digitalRead(sw2)==1){

lcd.clear();

if(digitalRead(sw1)==0){set_daya++;if
(set_daya>200){set_daya=1;}}

lcd.setCursor(0,0);

lcd.print("PENGATURAN");

lcd.setCursor(0,1);

lcd.print("Daya= ");

lcd.print(set_daya);

delay(200);

}

lcd.clear();

lcd.setCursor(0,0);

lcd.print("TERSIMPAN.....");

delay(3000);

}
```